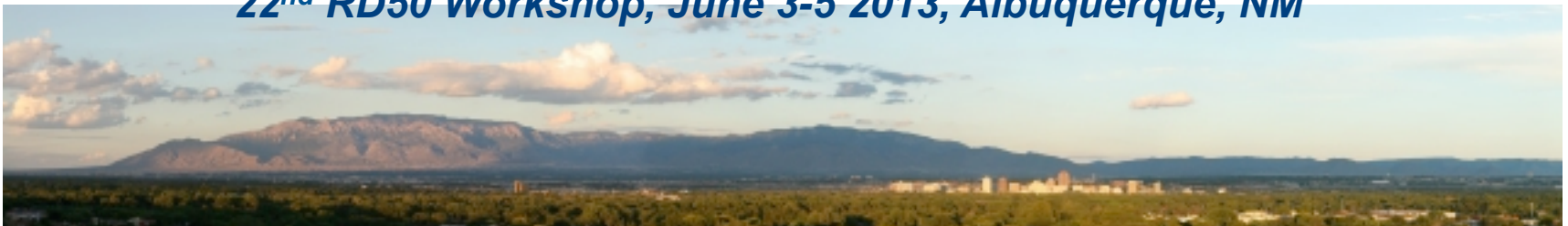




Radiation Damage of the ATLAS Pixel Sensors Using Leakage Current Measurement System

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(on behalf of ATLAS Collaboration)
University of New Mexico

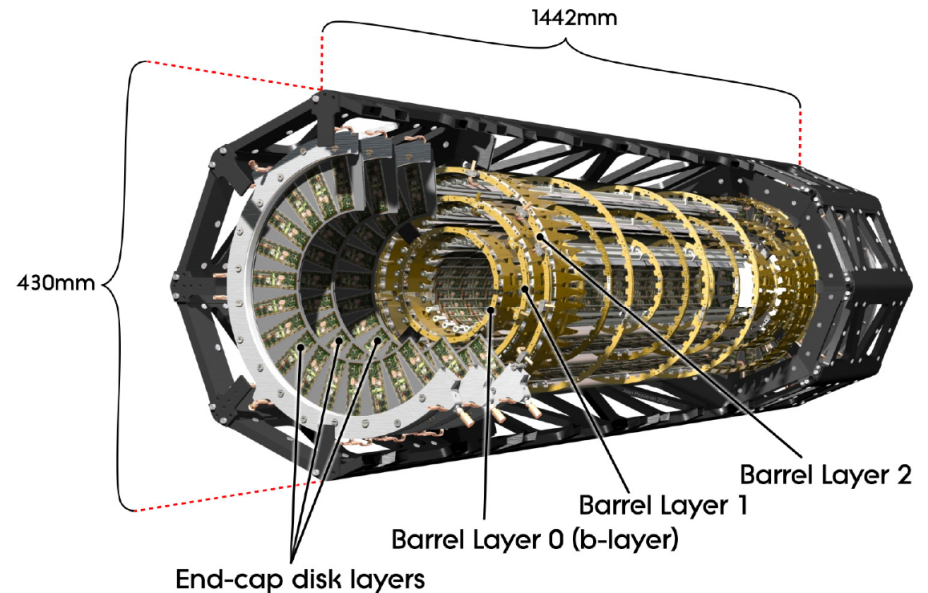
22nd RD50 Workshop, June 3-5 2013, Albuquerque, NM



Outline

- Introduction
- Radiation Damage
- Annealing
- Leakage Current Measurement System
- Technical Solutions
- Current Measurement Board
- Leakage Current Data
- Summary

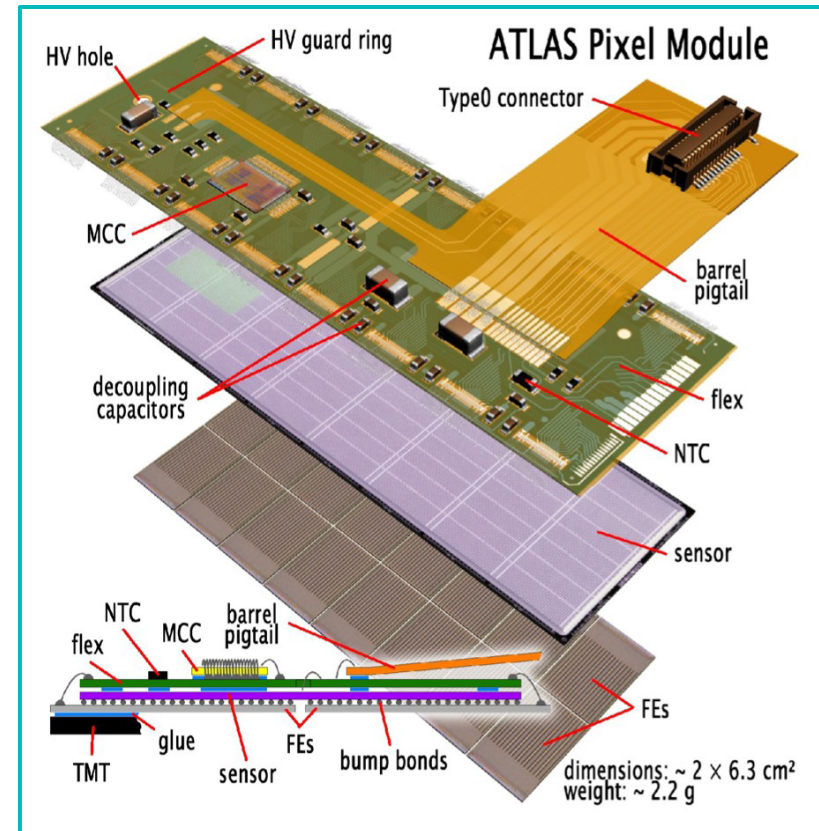
ATLAS Pixel Detector



Introduction (I)

ATLAS Pixel Detector: Geometry

- Planar n+ -on- n sensors on $256 \pm 3 \mu\text{m}$ thick n-bulk wafer
- Innermost layer: $r = 50.5 \text{ mm}$ w.r.t. beamline
 - Radiation tolerance $500\text{kGy} / 1 \times 10^{15} \text{ n}_{\text{eq}}/\text{cm}^2$
- evaporative cooling system integrated into support structure:
 - Operational average temperature: $T = -13^\circ\text{C}$
 - Scheduled maintenance warm-up periods: $T = +20^\circ\text{C}$
- The max. bias voltage spec: 600 V
 - while detector systems have been tested at bias $\text{HV} \leq 1\text{kV}$



Introduction (II)

ATLAS Pixel Detector: Geometry

Barrel Region of ATLAS Pixel Detector

Layer Number	Mean Radius [mm]	Number of Staves	Number of Modules	Number of Channels	Active Area [m ²]
0	50.5	22	286	13,178,880	0.28
1	88.5	38	494	22,763,520	0.49
2	122.5	52	676	31,150,080	0.67
Total		112	1456	67,092,480	1.45

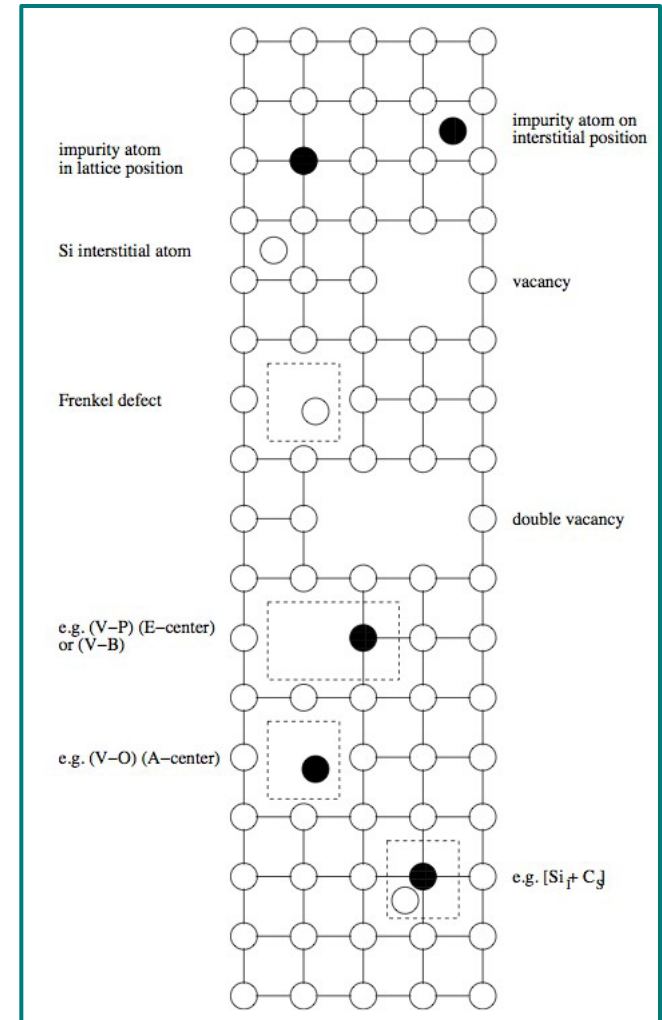
End Cap Region of ATLAS Pixel Detector

Disk Number	Mean z [mm]	Number of Sectors	Number of Modules	Number of Channels	Active Area [m ²]
0	495	8	48	2,211,840	0.0475
1	580	8	48	2,211,840	0.0475
2	650	8	48	2,211,840	0.0475
Total one endcap		24	144	6,635,520	0.14
Total both endcaps		48	288	13,271,040	0.28

- **Total number of modules: $1456 + 2 \times 144 = 1744$**
- **Each sensor with 46,080 channels ...**
- **In total: $67,092,480$ (barrel) + $2 \times 6,635,520$ (disks) = $80,363,520$ channels**
- **Total instrumented area: $\sim 1.7 \text{m}^2$**

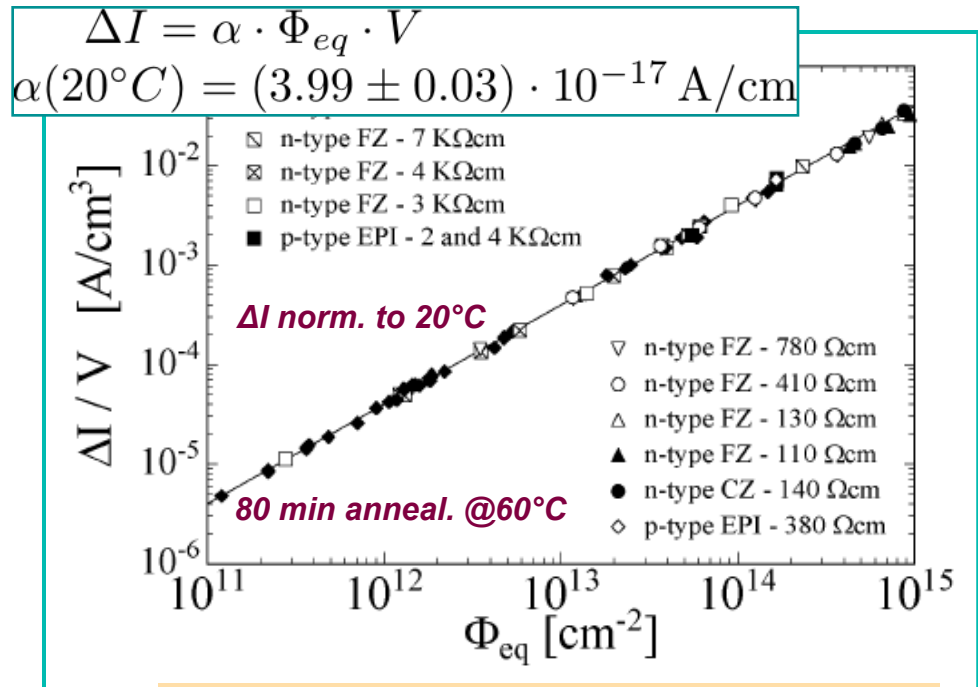
Radiation Damage (I)

- **Dominant radiation damage**
 - Displacement defects in a bulk
 - Due to Non-Ionizing Energy Losses (NIEL)
 - Flow of charged π^\pm from ATLAS I.P.
- **Three effects:**
 - **Charge carrier trapping**
 - localized trapping centers
 - if the time to re-emit the trapped charge carrier is longer than the shaping time then the charge collection efficiency degrades
 - loss of induced charge causing reduction of signal
 - **dominant at $\Phi \geq 1 \times 10^{15} n_{eq}/cm^2$**
 - **Leakage current**
 - electron-hole generation on defect centers increase the leakage current, degrading signal/noise and requiring more cooling ($-13^\circ C$)
 - **Change of N_{eff} concentration and voltage V_{dep}**
 - effectively inversion into “p-type”
 - increasing of V_{dep}
 - requiring higher bias voltages
 - **effect should be visible at $\Phi < 1 \times 10^{15} n_{eq}/cm^2$**

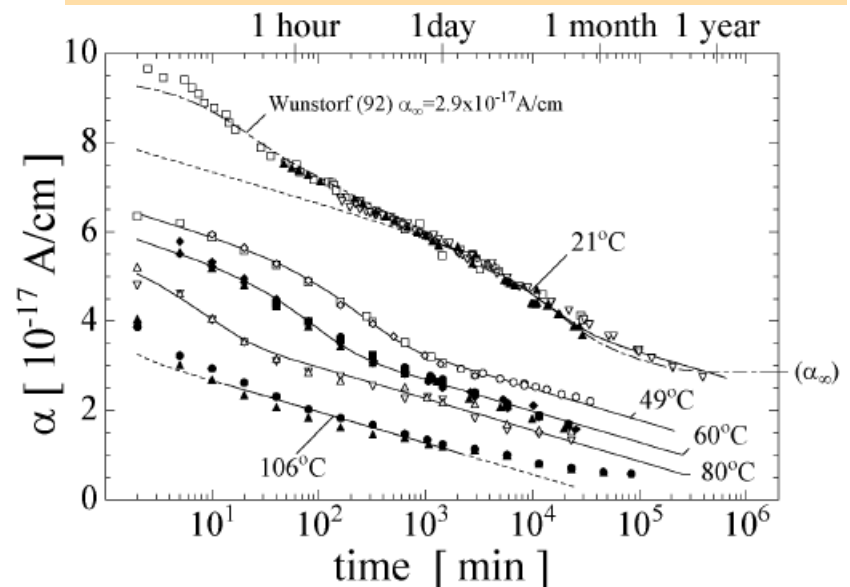


Annealing (I)

- Defects in a crystal bulk can anneal
 - Diffusion: defects migrating until getting at sinks; form new complex defects.
 - examples: interstitials and vacancies mobile at room temperatures
 - Dissociation.
 - Strongly temperature dependent
 - Have different activation energies depending on the defect type
- Trapping: beneficial annealing
 - the electron trapping times increase for realistic annealing times resulting in higher signal yield
- Leakage current: beneficial annealing
 - leakage current reduced during annealing; typically factor of 2 can be annealed
 - then operation at cool temperatures



Source: M. Moll et al., NIM A426 (1999) 87



Annealing (II)

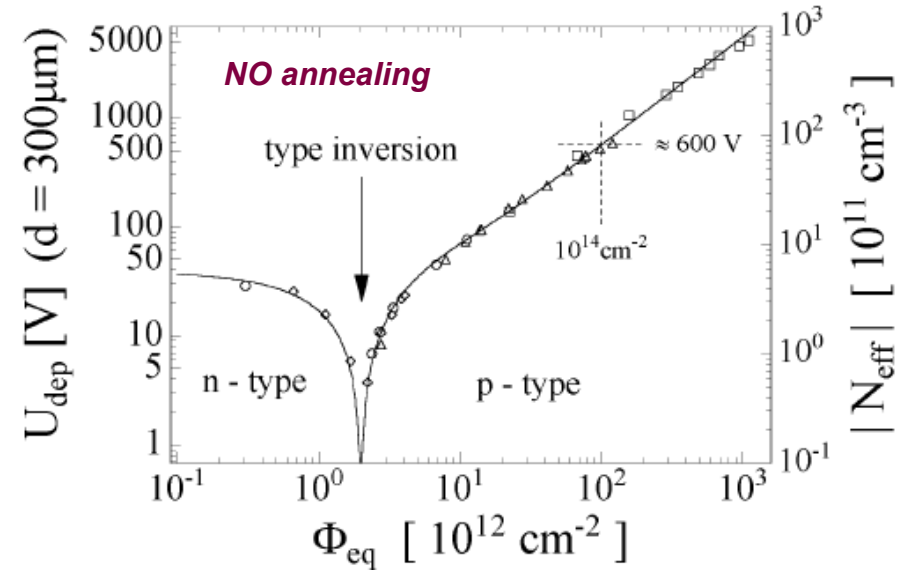
- Depletion voltage U_{dep} and effective doping concentration $|N_{eff}|$
 - the change observed for $|N_{eff}|$ ($=U_{dep}$) measured immediately after irradiation
 - donor removal and acceptor generation finally result in *n-type to p-type inversion* of the bulk
 - in contrast to the damage rate, α , depletion voltage V_{dep} (N_{eff}) time dependence is subject to both **beneficial**, N_A and **reverse** annealing, N_Y :

in contrast to the damage rate, α , depletion voltage V_{dep} ($|N_{eff}|$) time dependence is subject to both beneficial, N_A and reverse annealing, N_Y .

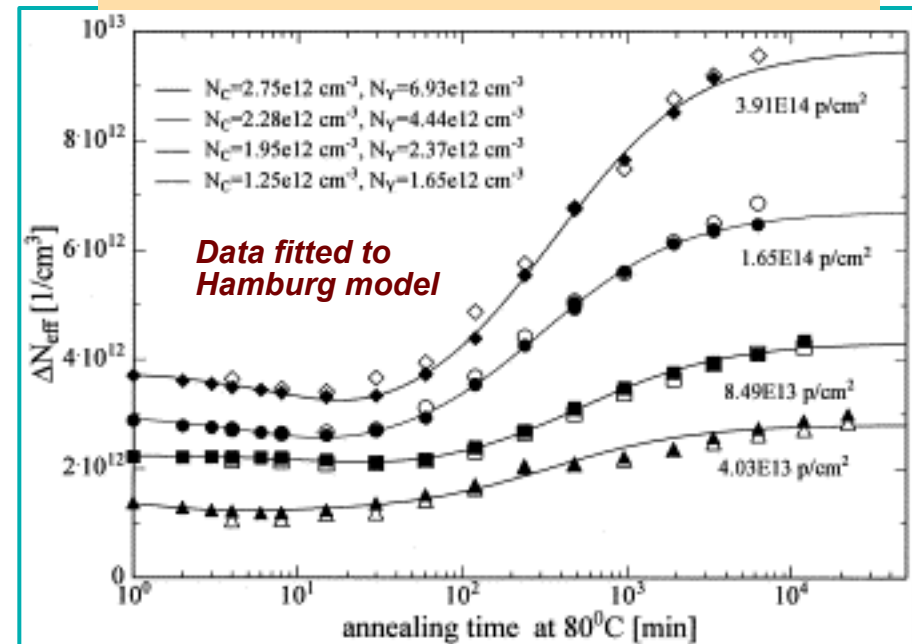
Hamburg Model:

$$\begin{aligned} \Delta N_{eff}(\Phi_{eq}, t(T_a)) &= N_{eff,0} \\ &- N_{eff}(\Phi_{eq}, t(T_a)) \\ \Delta N_{eff}(\Phi_{eq}, t(T_a)) &= N_A((\Phi_{eq}, t(T_a))) \\ &+ N_C(\Phi_{eq}) \\ &+ N_Y((\Phi_{eq}, t(T_a))) \end{aligned}$$

Source: G. Lindström et al., NIM A426 (1999) 1



Source: G. Lindström et al., NIM A466 (2001) 308



Realistic Annealing Predictions (III)

- Realistic LHC scenario for ATLAS pixel sensors

- Hamburg model is applied

- Warm-up Scenarios for maintenance periods:

- 3 days @ $T_A=20^\circ\text{C}$ and 14 days @ $T_A=17^\circ\text{C}$

- 30 days @ $T_A=20^\circ\text{C}$

- 60 days @ $T_A=20^\circ\text{C}$

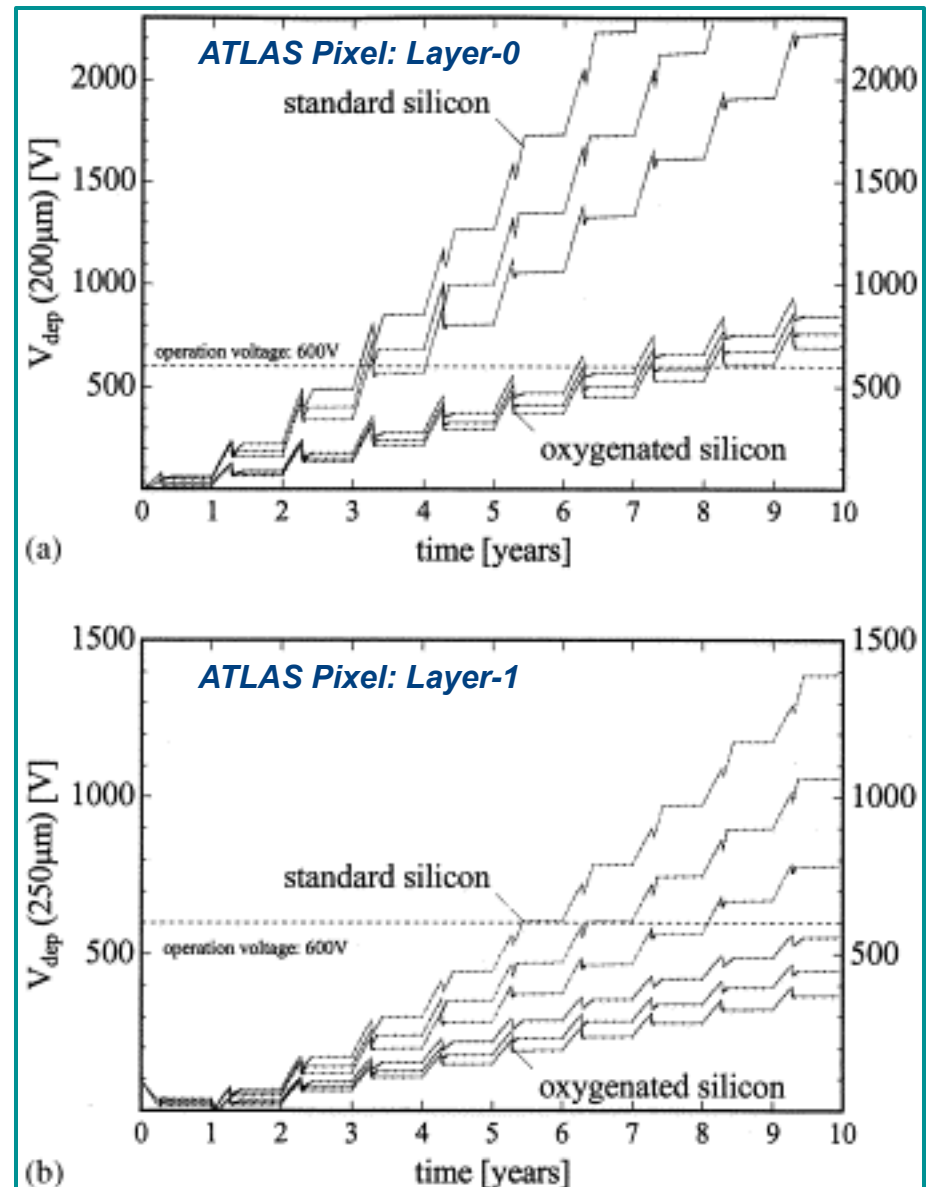
- **beams ON** : $T_{oper} = -13^\circ\text{C}$

- to keep depletion voltage for the planned running period

$V_{dep} \leq 600\text{V}$ (ATLAS Pixel spec.)

the reverse annealing should be suppressed:

- the pixel detector modules must be **kept cold** when **beams are OFF** except of a short maintenance period



Source: R. Wunstorf, NIM A466 (2001) 327

Leakage Current Measurement System

- Monitoring of ATLAS pixel sensors with leakage current measurements done in situ and in real time
 - *no special runs required*
- Leakage current is measured for individual sensors (typically 4 per half-stave) with staves instrumented evenly over every layer
- The currents should be monitored over long period
 - wide dynamical range
 - $\Phi_{1\text{MeV eq}} \leq 1.0 \times 10^{15} \text{ cm}^{-2}$
- Differential analysis of the radiation damage in various parts of the detector vs integrated lumi ($\propto \Phi_{\text{eq}}$)
- Measure the leakage currents against integrated luminosity ($\propto \Phi_{\text{eq}}$) and compare with the model predictions
 - *calibrate the model parameters with experimental data*
 - *use the adjusted model to project the depletion voltage development in time at various LHC / ATLAS data taking scenarios*

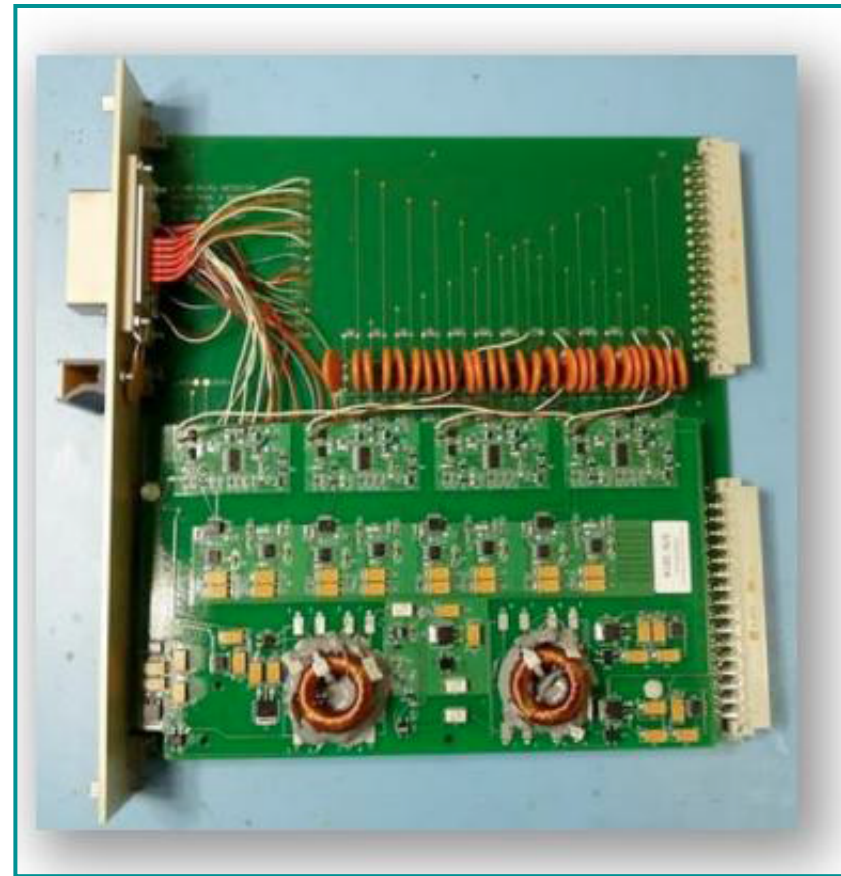
Technical Solution: Leakage Current Measurement System

- Main system unit: Current Measurement Board (or *CMB*)
 - *Direct measurement of an individual pixel sensor module leakage current via HV lines*
- Implemented: within the reconfigurable HV patch panel (or *HVPP4*) between HV cables coming from Pixel detector (*PP1*) and power supply (*Iseg*) HV channels
 - **Current Measurement Board (*CMB*)** is mounted on a corresponding HV fan-out board of *HVPP4*
- Power Supply (*Iseg*) current measurements
 - the power is delivered per half-stave comprising 6 or 7 modules
 - *the measurements of a leakage current drawn by ganged 6 or 7 modules are provided*
- The measured current values are digitized, transmitted via data (CAN) bus to the DCS by CERN developed digital board (*ELMB*)
 - 64 digital channel
 - served by 16 bit ADC
 - digitizing voltages fed by *CMB*
 - current data from *Iseg* power supply channels
- PVSS software is reading out the data from *ELMB* boards and downloading the data to DCS database (large DCS storage)
- **Physics analysis** on the radiation damage proceeds offline using data accessed from DB

Current Measurement Board (I)

- $(0.05 \mu\text{A}, 2 \text{mA})$, dynamical range of $\sim 0.4 \times 10^5$
- CMB output voltage: $(0, 5) \text{V}_{\text{DC}}$ to comply the digital board ELMB specs
- the circuitry: a current to frequency converter, optically coupled to a frequency to voltage converter
- the board is a multi-layer PCB with
 - 4 current measurement circuits
 - high gain + low gain channels / circuit : 4×2
- the pairs of channels are isolated from each other and from the pixel module readout system

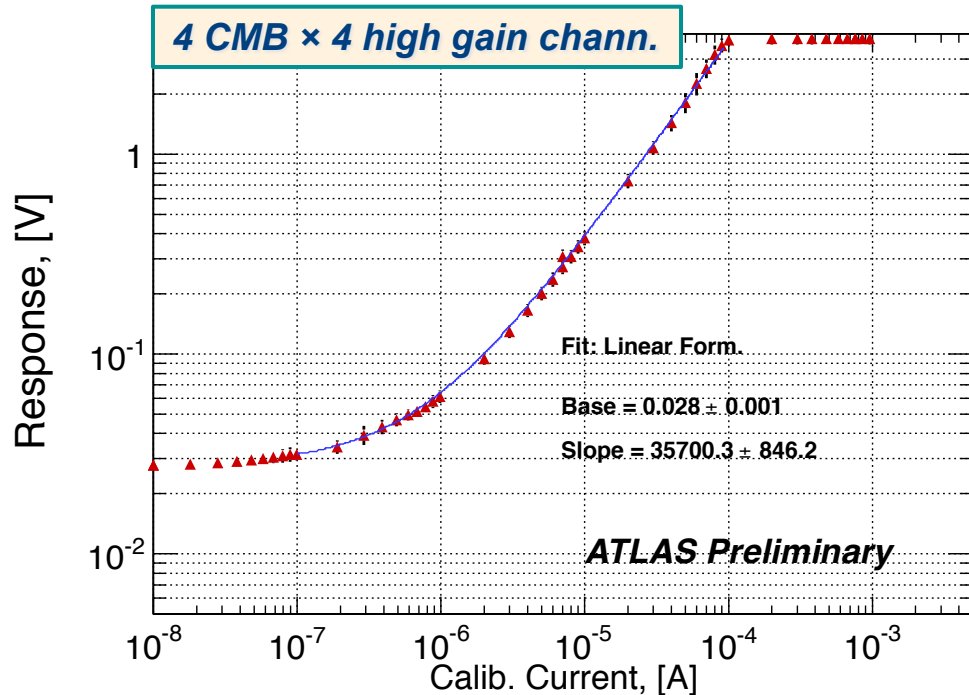
NO in situ calibration system is available.



- realistic voltage range (present setting) for ADC: $(0.0, 1.0) \text{V}$
 - $(0, 65535)$ of 16-bit
 - high gain: $LSB = 15.3 \mu\text{V} \approx 0.5 \text{nA}$
 - low gain: $LSB = 15.3 \mu\text{V} \approx 18 \text{nA}$

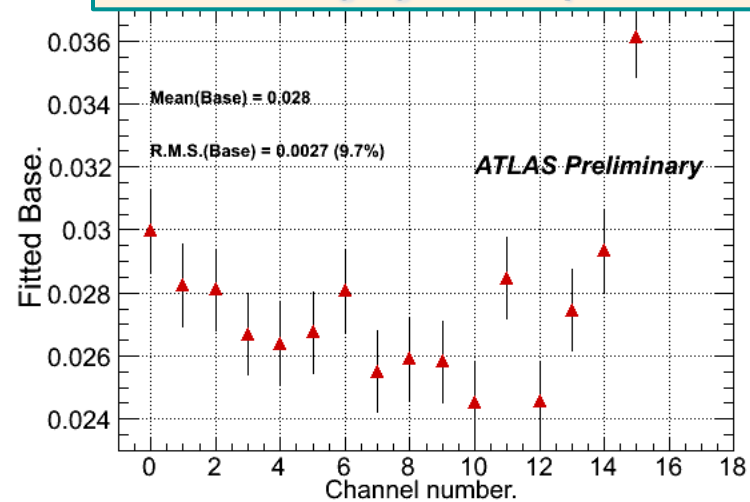
Current Measurement Board: Calibration (II)

Calibration runs made with a test stand on surface (bldg. SR1)

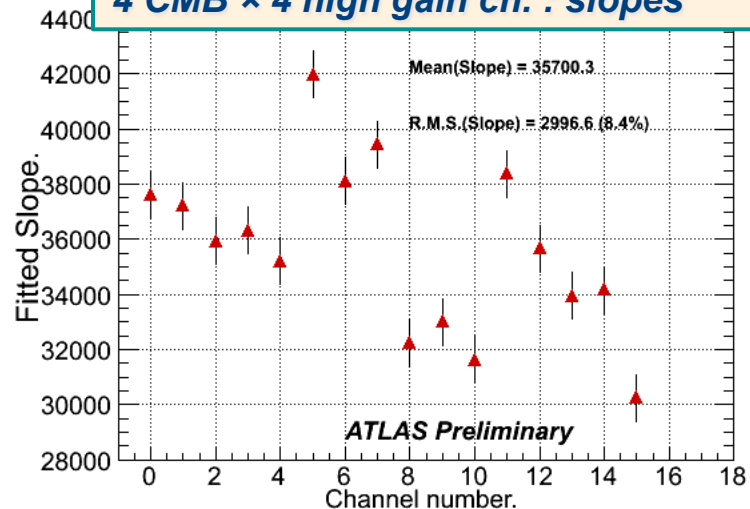


Fit individual channels with linear form: and store intercept (pedestal) and slope per CMB/channel

4 CMB \times 4 high gain ch. : pedestals



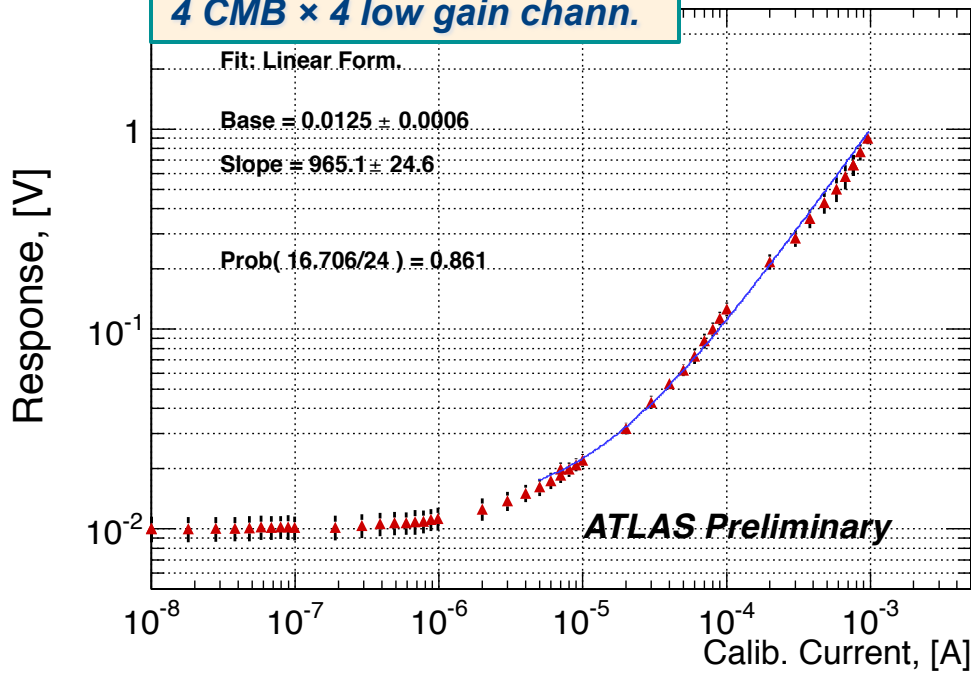
4 CMB \times 4 high gain ch. : slopes



Current Measurement Board: Calibration (III)

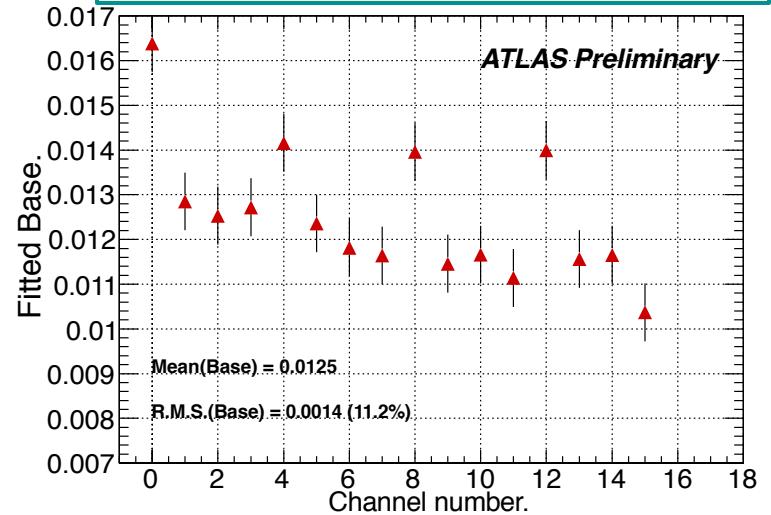
Calibration runs made with a test stand on surface (bldg. SR1)

4 CMB × 4 low gain chann.

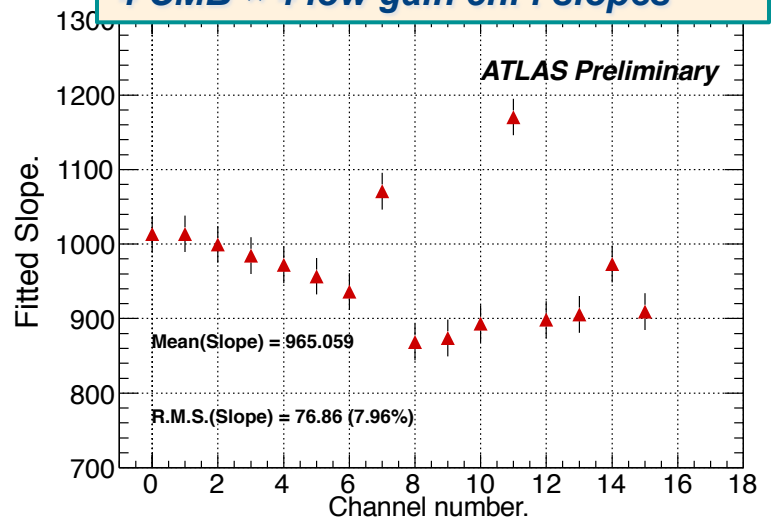


Fit individual channels with linear form:
and store intercept (pedestal) and slope
per CMB/channel

4 CMB × low gain ch. : pedestals



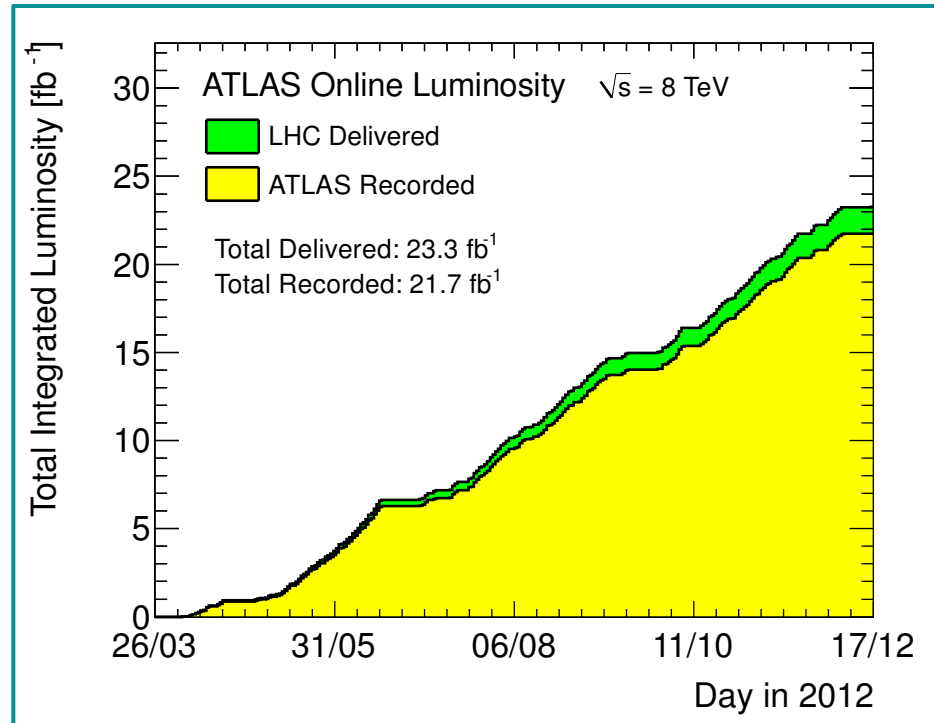
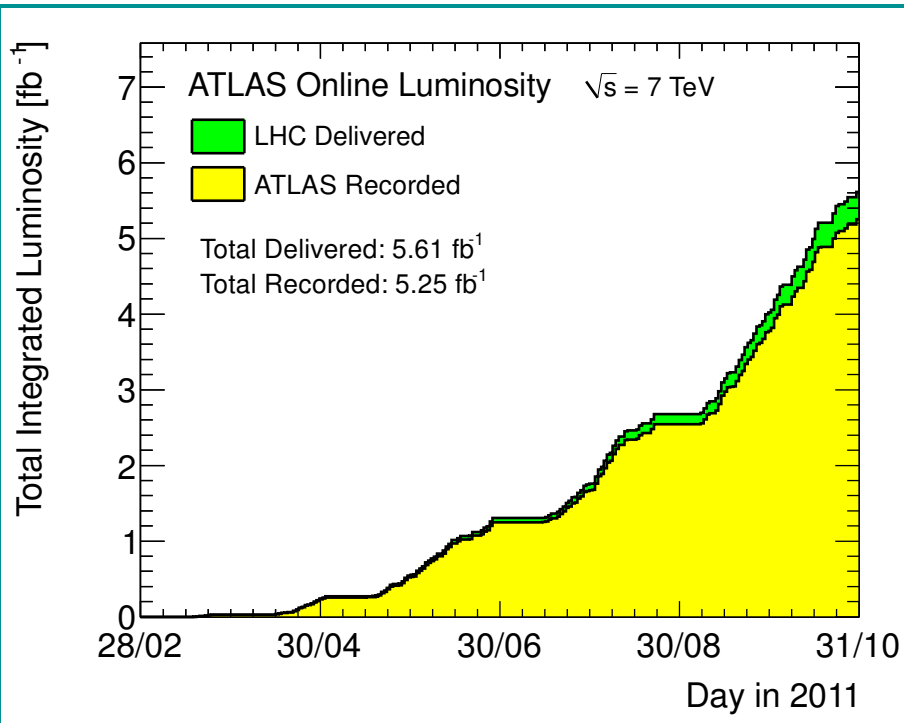
4 CMB × 4 low gain ch. : slopes



Current Measurement Boards: Status (IV)

- Barrel only
- Select pixel modules to instrument the barrel area in a uniform way along z and ϕ
- Layer 0 (innermost):
 - **21 CMBs installed**
 - **$21 \times 4 = 84$** modules instrumented
- Layer 1 (intermediate):
 - **16 CMBs installed**
 - **$16 \times 4 = 64$** modules instrumented
- Layer 2 (outermost):
 - **16 CMBs installed**
 - **$16 \times 4 = 64$** modules instrumented
- The hardware installation, analog CMB and digital ELMB boards, completed in June 2012

Luminosity Collected: 2011-2012



$$\int \mathcal{L} dt \propto \Phi_{1\text{MeV} \text{ eq}}$$

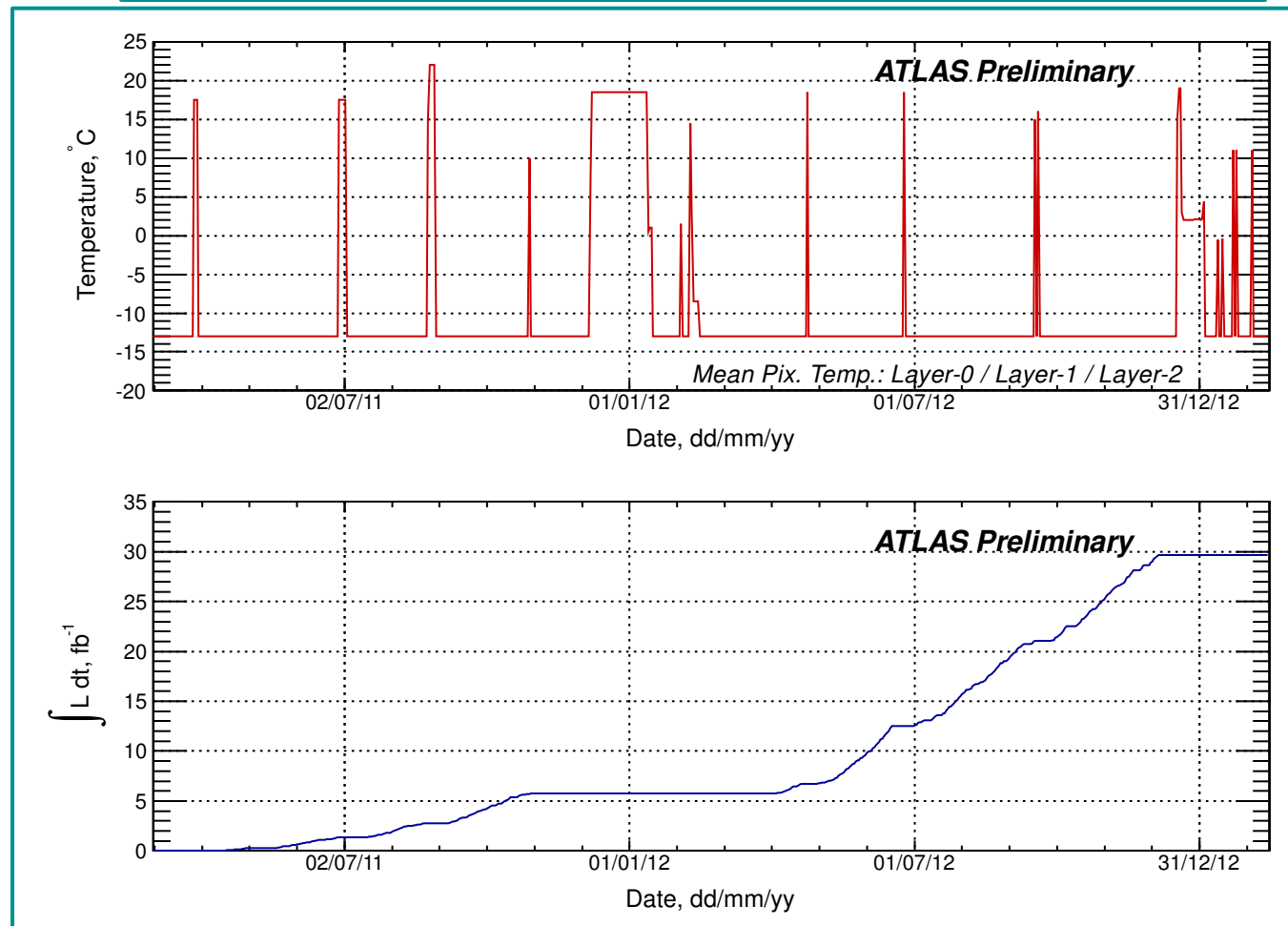
$$\int \mathcal{L} dt = 5.61 \text{ fb}^{-1} (\sqrt{s} = 7 \text{ TeV})$$

$$+ 23.3 \text{ fb}^{-1} (\sqrt{s} = 8 \text{ TeV}) \approx 29 \text{ fb}^{-1}$$

Temperature and Luminosity Profiles

Data from D. Münstermann and A. Schorlemmer (ATLAS/Geneva, Göttingen)

- Temperature per day 2011-2012 profile used in the analysis
- Operational $t = -13^{\circ}\text{C}$, very stable
- Technical stops, winter shutdowns, cooling failures are the main causes of warm-ups
- Actually, use readings from temperature sensors mounted on pixel modules
- $\int \mathcal{L} dt$ per day, 2011-2012 profile

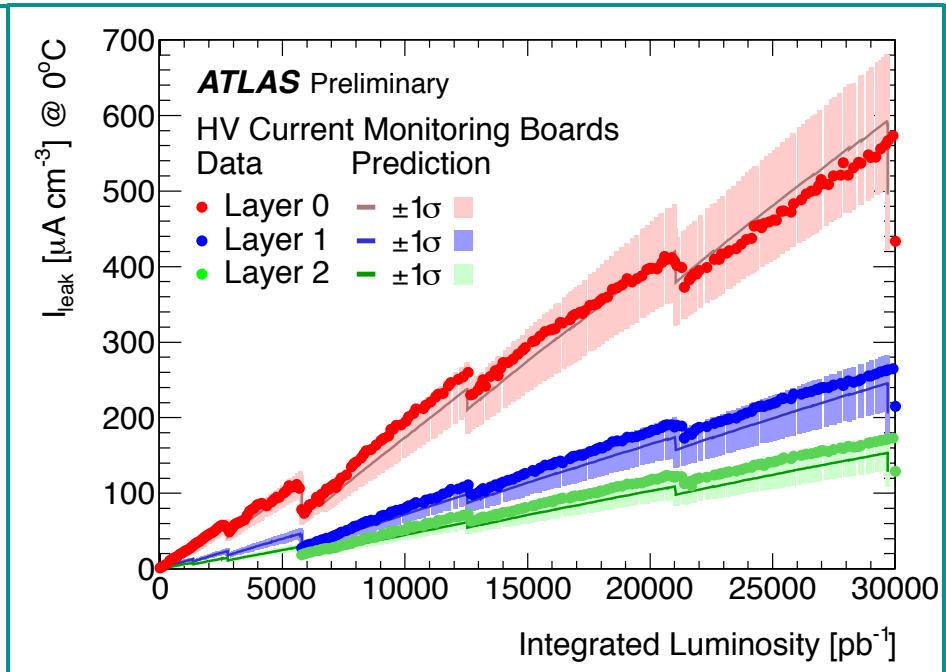
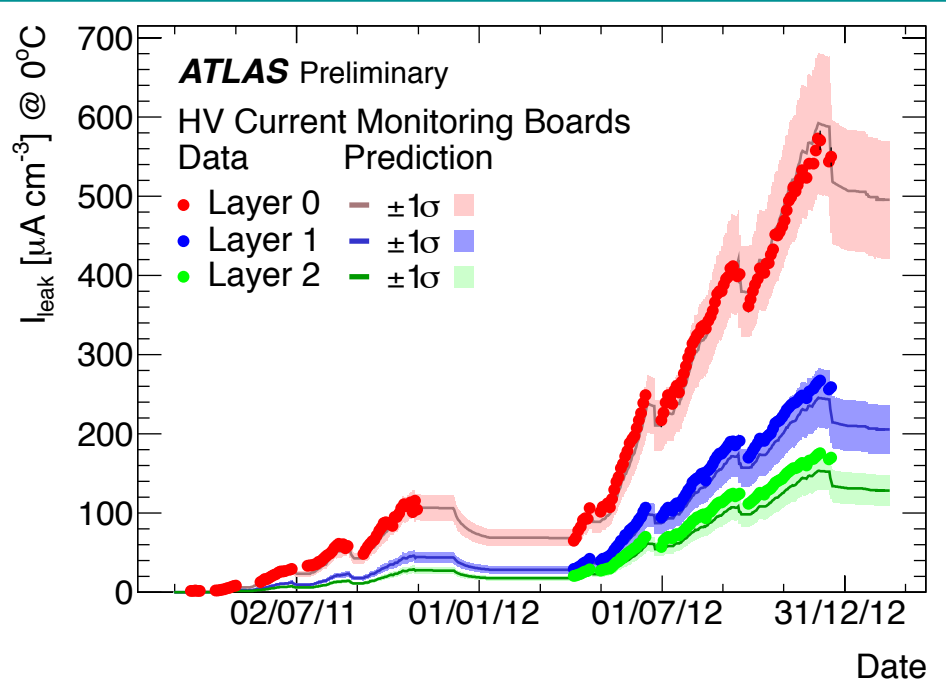


$$I(T) = I(T_R)/R(T), \quad R(T) = (T_R/T)^2 \cdot \exp\left(-\frac{E_g}{2k_B}(1/T_R - 1/T)\right)$$

$$E_g = 1.21 \text{ eV}, \quad T_R(^{\circ}\text{K}) = 0^{\circ}\text{C} + 273.15^{\circ}$$

Leakage Current Data

- Exp data, (voltage, V) per chann. converted to (current, A) per chann.
 - most recent calibrations per channel made on surface (SR1)
 - cross-calibration with Iseg power supply current data
- Current values renormalized from $t_{oper.} \approx -13^{\circ}C$ to $t = 0^{\circ}C$; per channel corr.
- Mean current value per Layer-0, Layer-1, Layer-2 are presented \Rightarrow
- $\Phi_{1MeV n} \propto \int \mathcal{L} dt$, using Fluka+Phojet
- Model predictions: O. Krasel, D. Münstermann, J. Weber A. Schorlemmer (ATLAS/ Dortmund, Geneva, Göttingen)



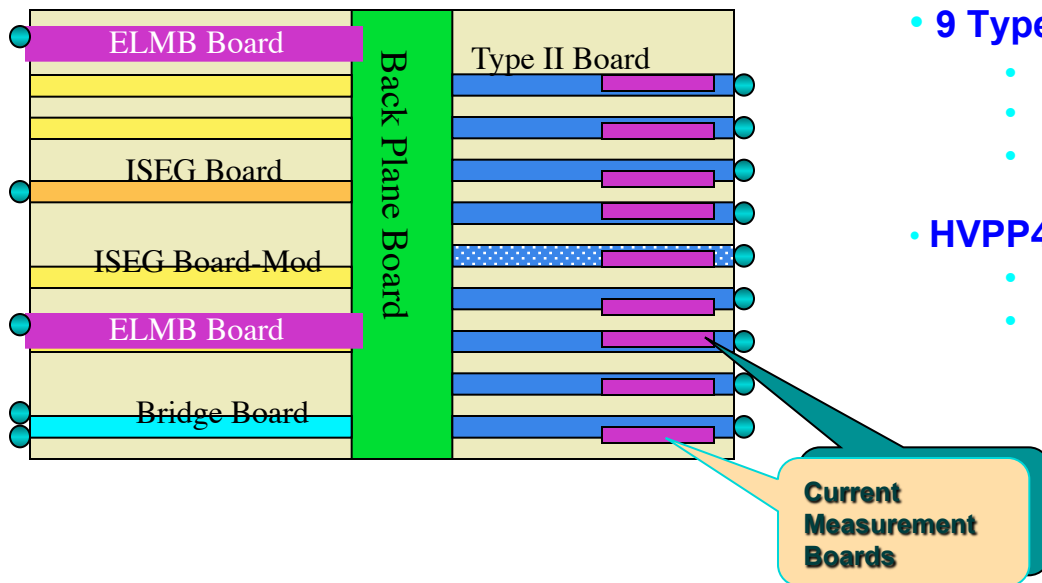
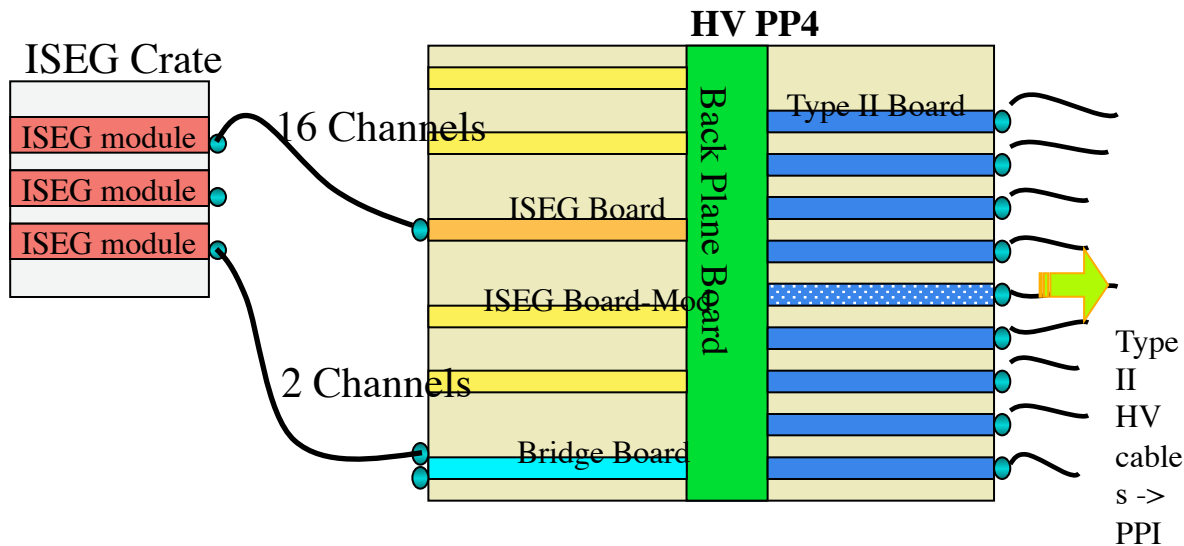
Summary

- A dedicated hardware to measure the leakage current in ATLAS pixel sensors has been implemented
 - available for the online monitoring
 - the stored data are used for the radiation damage analysis
- The radiation damage of the pixel sensor modules has been observed and measured for the 2011-2012 data taking period
 - the radiation damage data has been obtained in situ for the sensors of the ATLAS Pixel detector at its running conditions
- The measurements are compared with the model predictions made for the corresponding luminosity / fluence profile over 2011-2012
 - the data to model agreement is quite good within $\pm 1\sigma$



Back up slides ...

Current Measurement Board (I)



• Present HVPP4 System:

- Fan-out of the bias-voltages from ISEG power supply modules
- 1744 pixel modules

• New HVPP4 System: extended with:

- **Current Measurement Boards** attached to the Type II boards
- Analog-to-digital conversion **ELMB boards**

• 9 Type II boards / VME crate

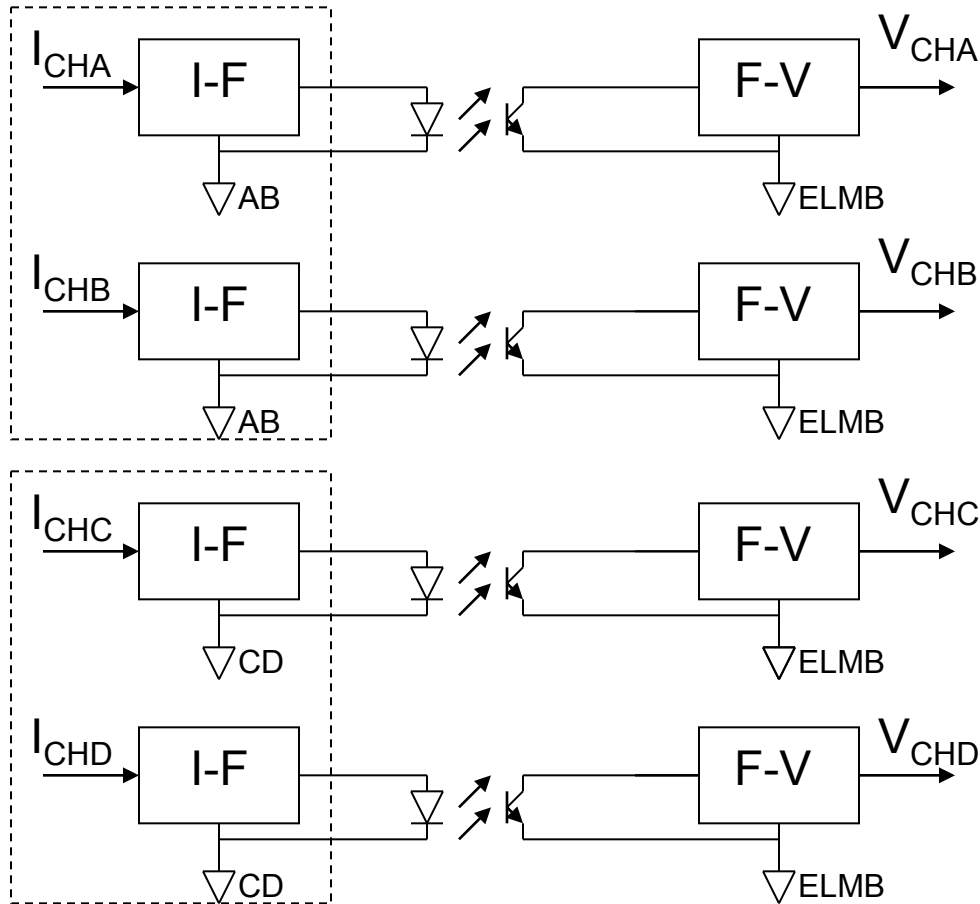
- 4 cha. / current meas. board
- (< 9) × 4 cha. / crate
- 2 ELMB board to digitize and send data

• HVPP4 Total: 16 VME crates

- $16 \times 9 \times 4 = 576$ channels
- *Some amount of channels will not be used due to complicated mapping*

Current Measurement Board (III)

Current Monitor Scheme



- Circuit is a current-frequency converter
- Optically coupled to a frequency-voltage converter.
- 4 circuits per board
- Isolated in pairs of channels from each other and from the readout system

Leakage Current (I)

- Current Measurements for every pixel module provide the powerful tool to monitor the status of every sensor and hence the quality of ATLAS Pixel Detector data
- Use current measurement data to estimate the fluence Φ [cm^{-2}]
- Every pixel module is equipped with temperature probe and the data are readout into PvssDb
- The current measurement data should be corrected by the temperature factors: \Rightarrow

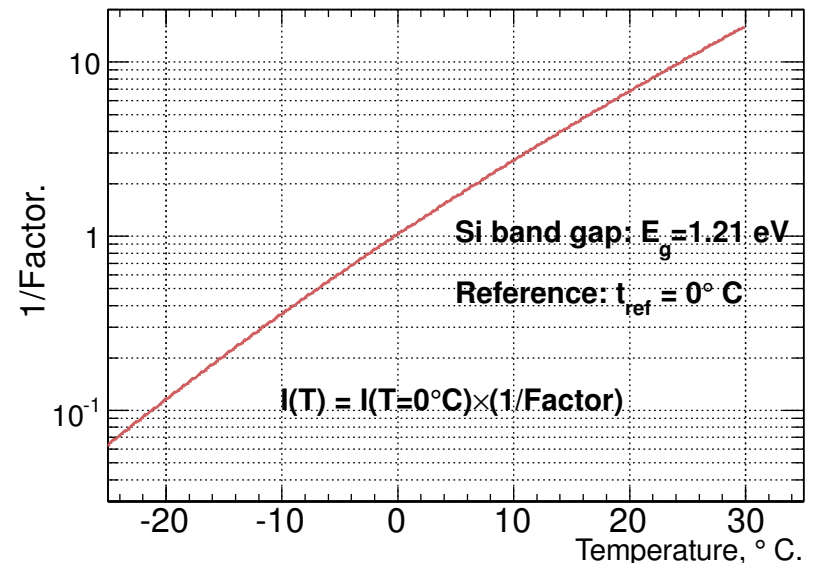
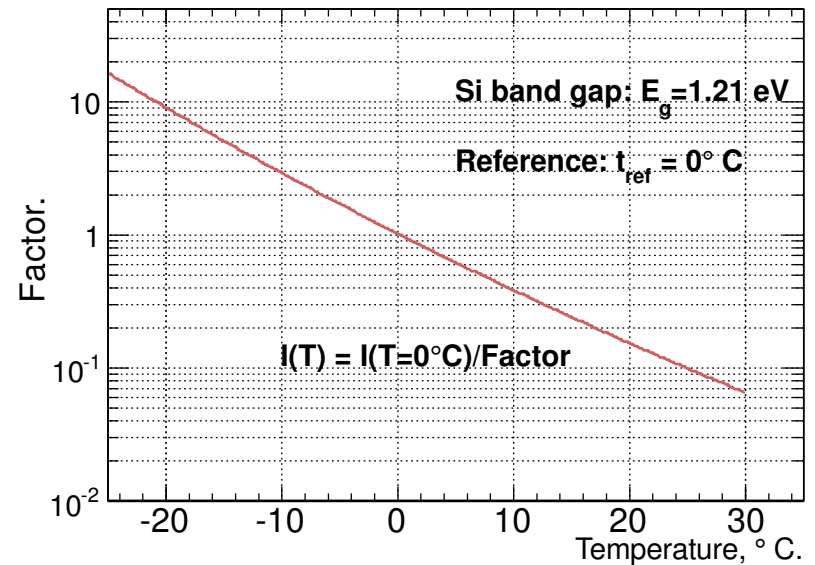
- Corrections are made to

$$T_R = (273.15 + 0)^\circ\text{K}$$

$$E_g = 1.21 \text{ eV (per Chilingarov)}$$

$$I(T) = I(T_R)/R(T), \text{ where}$$

$$R(T) = (T_R/T)^2 \cdot \exp\left(-\frac{E_g}{2k_B}(1/T_R - 1/T)\right)$$



Leakage Current (III)

Fluences at Pixel Detector Area

- Use the fluence calculations in ATLAS Inner Detector area made by ATLAS Radiation Task Force, CERN-ATL-GEN-2005-001

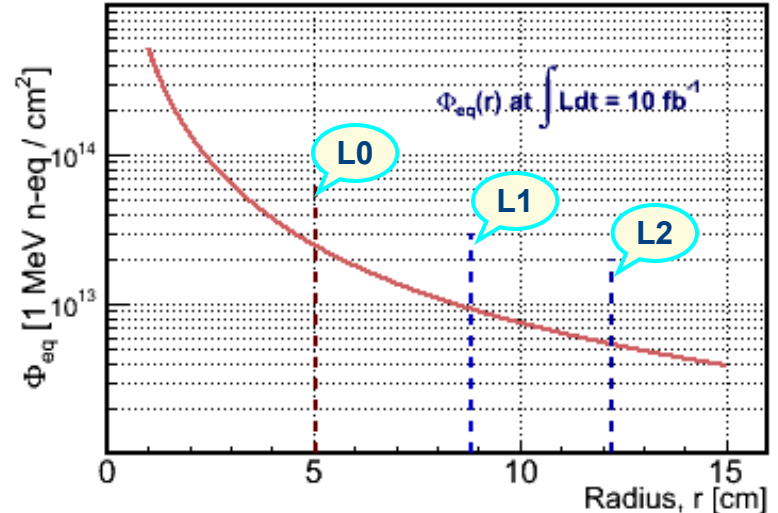
- Latest update by Ian Dawson in <http://indico.cern.ch/conferenceDisplay.py?confId=52704>
- 1 MeV n- equivalent $\Phi_{1\text{MeV-eq}}/1000\text{fb}^{-1}$
- LHC pp events with PHOJET+FLUKA
- The MC data fitted for $r \in (2, 20)\text{cm}$ with
- **Uncertainties of predictions:**
 - pp-generator: **$\approx 30\%$**
 - Calculation of 1MeV n- eq. using damage factors: **$\approx 50\%$**
 - **In total: $\approx 58\%$**

$$\Phi_{1\text{MeV}} = (a_1 \cdot r^{-2} + a_2 \cdot r^{-1}) / 1000 \text{ fb}^{-1},$$

where $a_1 = 4.93 \cdot 10^{16}$, $a_2 = 0.25 \cdot 10^{16}$

Use these parameterization to predict the fluences for Layer-0,1,2

ATLAS Collab.: Pixel Detector: Preliminary.



ATLAS Collab.: Pixel Detector: Preliminary.

